

# basics, measurement and modelling of BRTF

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## Outline

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- 5 getting BRTF into *Radiance*
  - paths
  - BRTF models
  - example: model fits in 1994
  - what *Radiance* is missing

- BRDF = bidirectional reflection transmission function
- BSDF = bidirectional scatter distribution function
- Bxxx = .. whatever..

all the same quantity:  
scattering of light at a surface

## what is this talk about ?

- sequence to simulation results:
  - 1 measure materials
  - 2 model material
  - 3 add geometry, sky, etc
  - 4 use model in simulation
- why bother measuring at all ?
  - 1 measured data better than assumptions
  - 2 no generic BRDF per type of material  
BRDF depends on surface finish
  - 3 manufacturers specs not always available
  - 4 recheck manufacturers specs
  - 5 compare materials by BRDF data

# solid angle

- solid angle of an object as seen from point  $P$ :  
project object onto sphere with radius  $r$  around  $P$   
$$\Omega := \frac{A_p}{r^2}$$
- unit: *steradian* [sr]
- dimensionless, full sphere:  $4\pi$ , hemisphere:  $2\pi$
- infinitesimal:  $d\Omega$ , finite:  $\Omega$  or  $\Delta\Omega$
- solid angle of a cone with opening angle  $\alpha$ :  
$$\Omega_{\text{cone}} = 2\pi \left(1 - \cos \frac{\alpha}{2}\right)$$

# radiant power

basic unit:

power transported by electromagnetic radiation

as described within concept of *photometry*  
(sometimes known as *radiance flux*)

three spectral flavours:

- spectrally integrated: *radiometric* [Watt]
- spectrally resolved: power per wavelength interval [Watt/nm]
- weighted by eye response and integrated: *photometric* [Lumen]

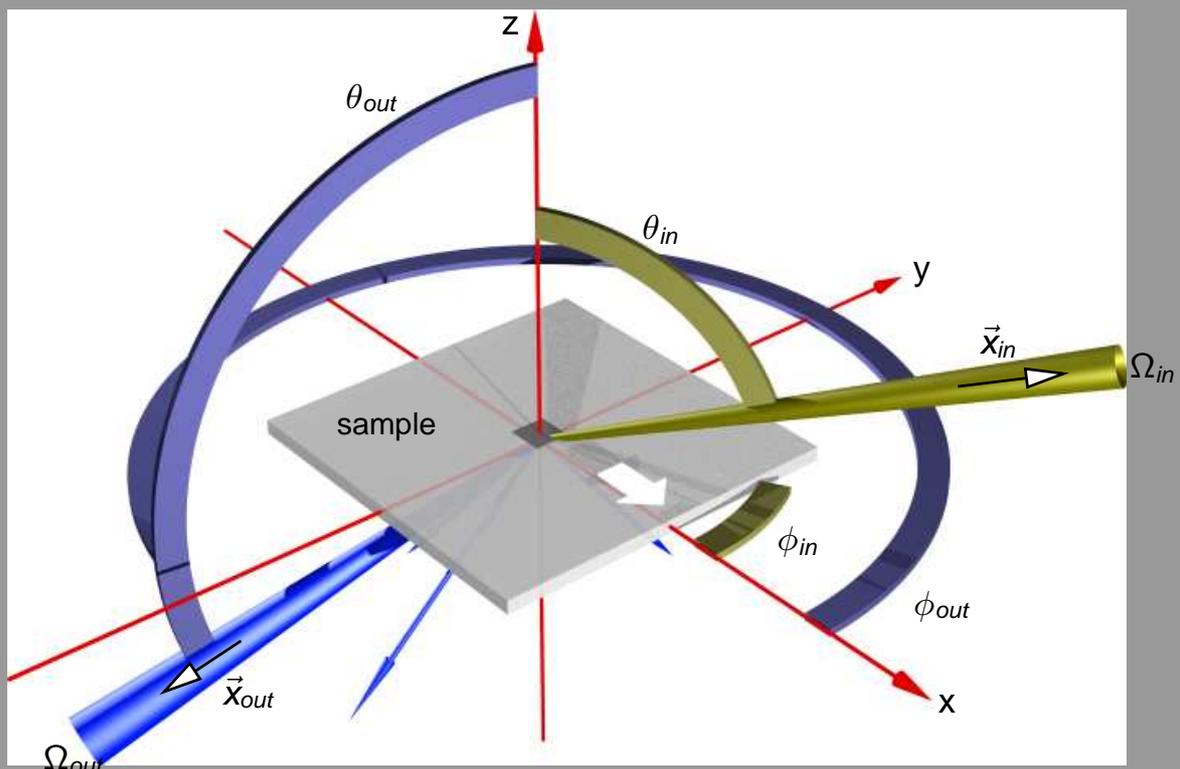
# derived quantities

quantities used most often:

- radiant power per area:  $\mathcal{E}$  [Watt/m<sup>2</sup>]
- radiant power per solid angle [Watt/sr] (*Radiant Intensity*)
- radiant power per solid angle and projected area,  $\mathcal{L}(\vec{x})$ , [Watt/(sr\*m<sup>2</sup>)] (*Radiance*)

... and equivalent photometric units

# coordinate system



## coordinate system

advantages of using these sample coordinates:

- standard polar coordinates
- one BRTF for front and back side of sample
- z-axis: surface normal  
x-axis: marked on sample
- direction written as  $\vec{x}$  or  $(\theta, \phi)$

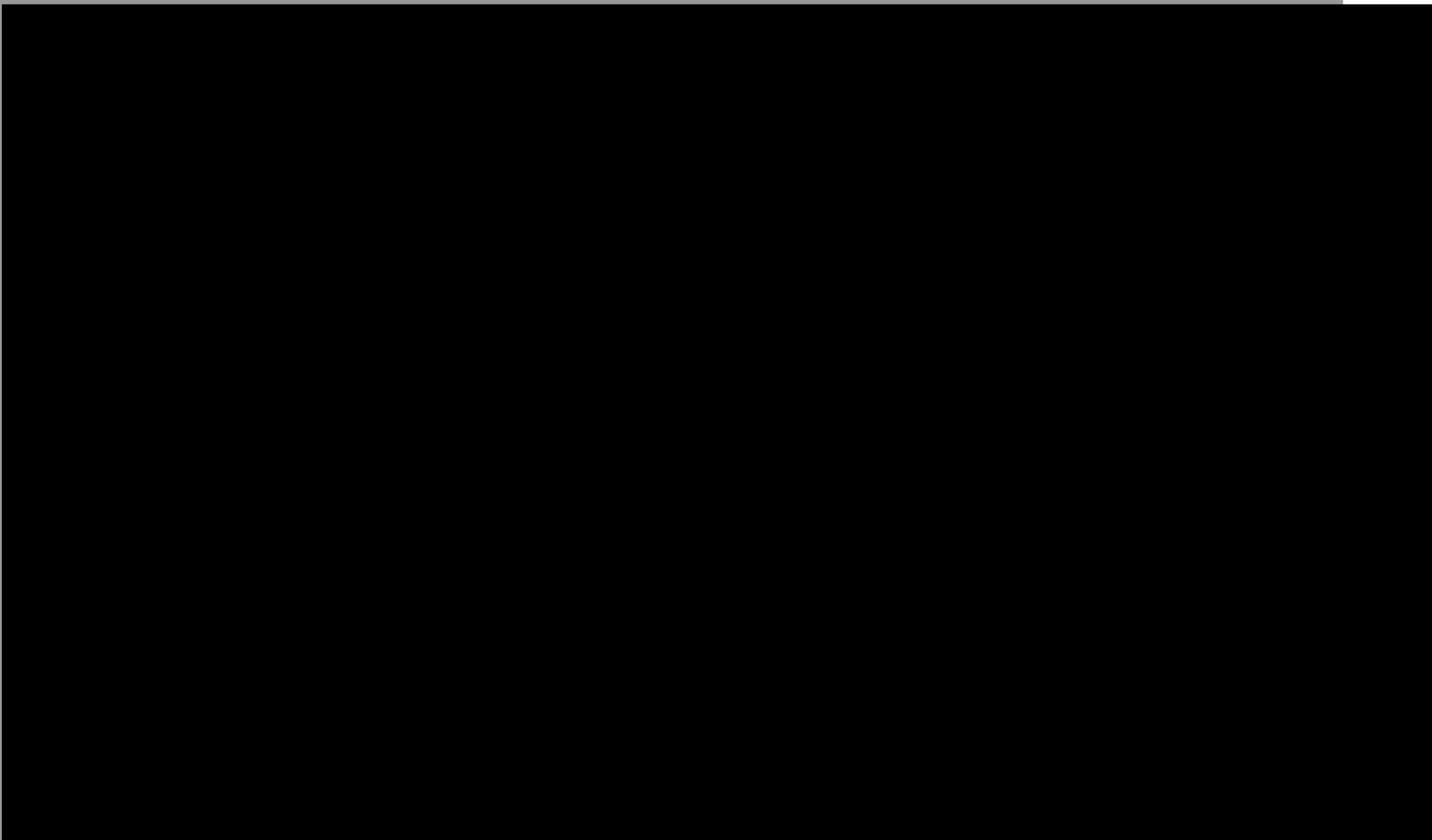
With incident light on the *front* surface:  $\theta_{in} = (0^\circ \dots 90^\circ)$ :

- $\theta_{out} = (0^\circ \dots 90^\circ)$  reflection,  
 $\theta_{out} = (90^\circ \dots 180^\circ)$  transmission.

Other coordinates possible, use transformations.

## demo

it's all easy ...



# defining formula

## Definition

$$\mathcal{L}_{out}(\vec{x}_{out}) = \int_{\vec{x}_{in}}^{\Omega_{in}=2\pi} BRTF(\vec{x}_{out}, \vec{x}_{in}) \mathcal{L}_{in}(\vec{x}_{in}) \cos(\alpha_{in}) d\Omega_{in}$$

- $\mathcal{L}_{in}$ : incident radiance from  $\vec{x}_{in}$
- $d\Omega_{in}$ : solid angle of incident light
- $\cos(\alpha_{in})$ : historic nuisance (*Lambert scatterer*)
- $\int_{\vec{x}_{in}}^{\Omega_{in}=2\pi}$ : integral over hemisphere
- $\mathcal{L}_{out}$ : outgoing radiance to  $\vec{x}_{out}$
- $BRTF > 0$  and may be  $> 1$
- $BRTF_{void}(\vec{x}_{out}, \vec{x}_{in}) = \delta(\vec{x}_{out} - \vec{x}_{in}) / \cos(\alpha_{in})$ , *Dirac Delta function*
- $BRTFc(\vec{x}_{out}, \vec{x}_{in}) := BRTF(\vec{x}_{out}, \vec{x}_{in}) \cos(\alpha_{in})$

# approximate formula

$$\mathcal{L}_{out}(\vec{x}_{out}) = \int_{\vec{x}_{in}}^{\Omega_{in}=2\pi} BRTF(\vec{x}_{out}, \vec{x}_{in}) \mathcal{L}_{in}(\vec{x}_{in}) \cos(\alpha_{in}) d\Omega_{in} \quad (1)$$

- assume  $\mathcal{L}_{in} > 0$  for small  $\Omega_{in}$  around  $\vec{x}_{in}^*$  only
- and assume  $BRTF = const$  over  $\Omega_{in}$
- then, and only then

$$BRTF(\vec{x}_{out}, \vec{x}_{in}^*) \approx \frac{\mathcal{L}_{out}(\vec{x}_{out})}{\mathcal{E}_{in}} \quad (2)$$

But:

This approximation is misleading and should be used with **caution**.

measured BRTF is always averaged over solid angles of detector  $\Delta\Omega_{out}$  and lamp  $\Delta\Omega_{in}$ :

$$\overline{BRTF}(\Delta\Omega_{in}, \Delta\Omega_{out}) := \frac{1}{\Delta\Omega_{in} \Delta\Omega_{out}} \int_{\vec{x}_{out}}^{\Delta\Omega_{out}} \int_{\vec{x}_{in}}^{\Delta\Omega_{in}} BRTF(\vec{x}_{out}, \vec{x}_{in}) d\Omega_{in} d\Omega_{out} \quad (3)$$

consequences:

this limit measurement of BRTF features.

↪ minimise  $\Delta\Omega_{out}$  and  $\Delta\Omega_{in}$

## transmission values from BRTF

transmission  $\tau$  from  $\Omega_{in}$  into  $\Omega_{out}$  is given by:

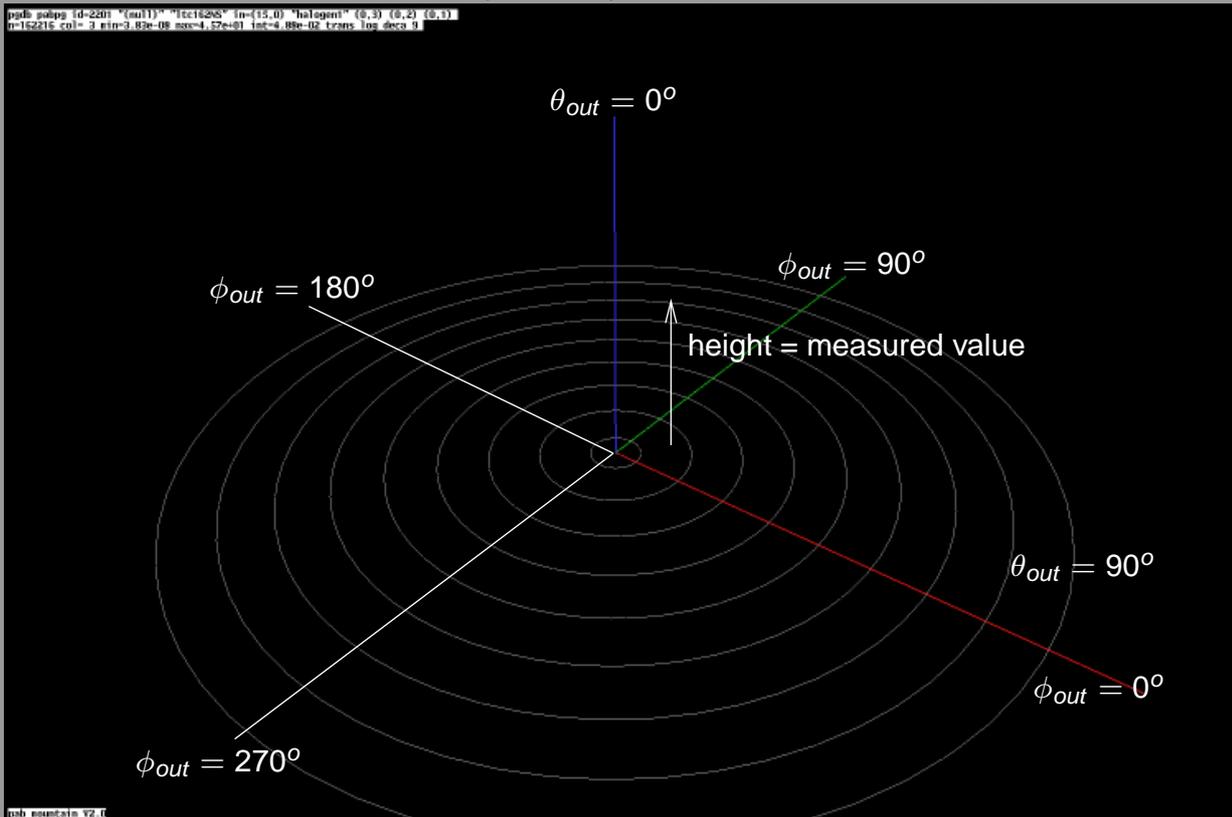
$$\tau(\Omega_{in}, \Omega_{out}) = \frac{\int_{\vec{x}_{out}}^{\Omega_{out}} \left\{ \int_{\vec{x}_{in}}^{\Omega_{in}} BRTF(\vec{x}_{out}, \vec{x}_{in}) \mathcal{L}_{in}(\vec{x}_{in}) \cos(\alpha_{in}) d\Omega_{in} \right\} \cos(\alpha_{out}) d\Omega_{out}}{\int_{\vec{x}_{in}}^{\Omega_{in}} \mathcal{L}_{in}(\vec{x}_{in}) \cos(\alpha_{in}) d\Omega_{in}} \quad (4)$$

Which for the *direct-hemispherical transmission* results in:

$$\tau_{dh}(\vec{x}_{in}) := \tau(d\Omega_{in}, 2\pi) = \int_{\vec{x}_{out}}^{2\pi} BRTF(\vec{x}_{out}, \vec{x}_{in}) \cos(\alpha_{out}) d\Omega_{out} \quad (5)$$

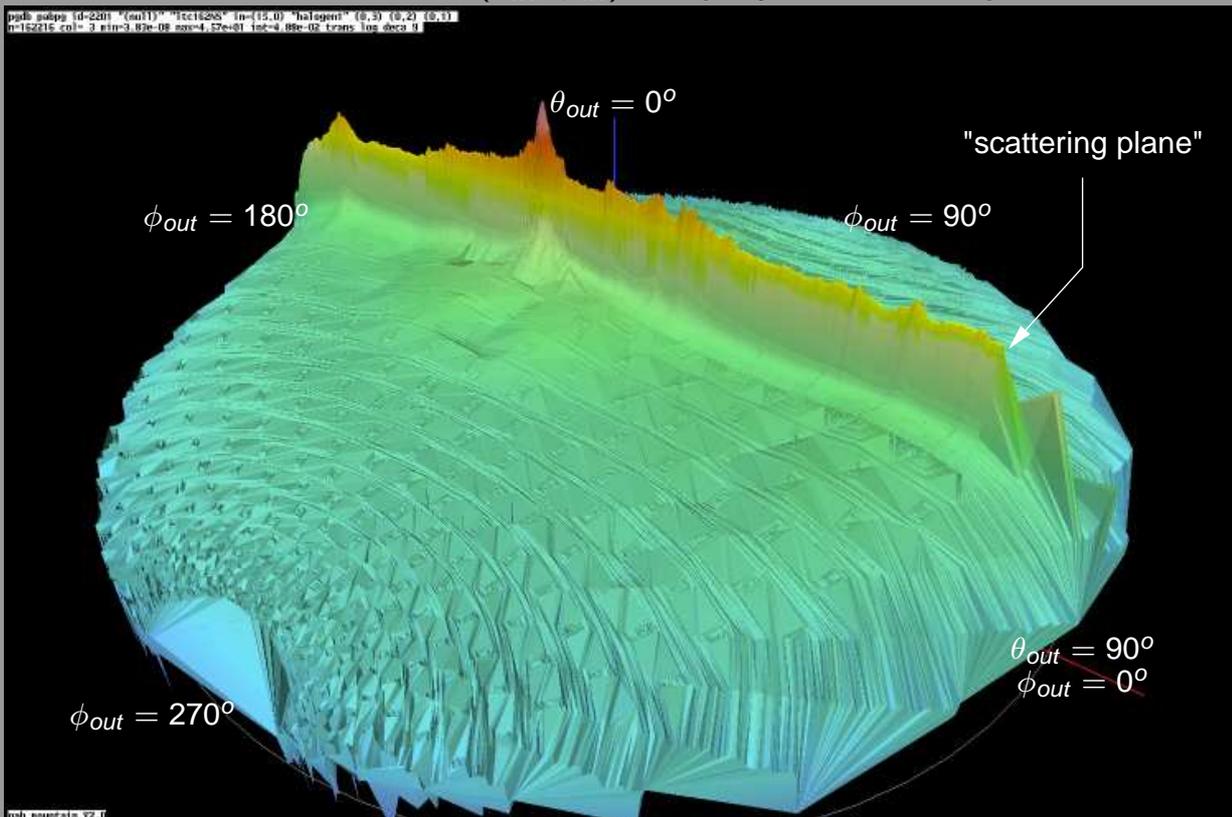
# visualising BRTF 3D

for one incident direction  $(\theta_{in}, \phi_{in})$ , display one hemisphere:



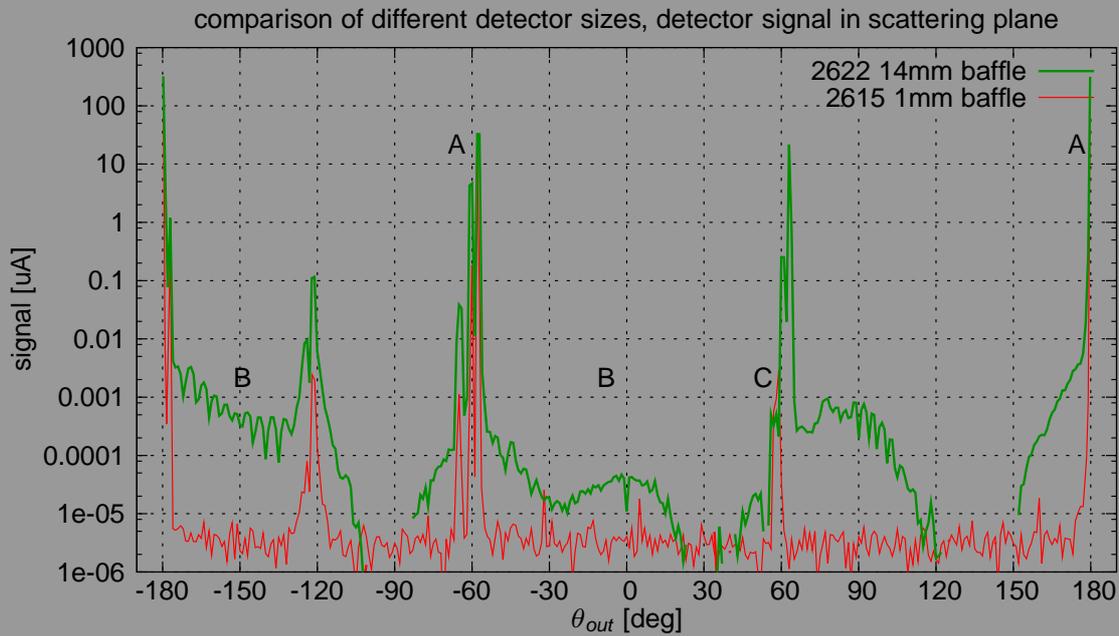
# visualising BRTF 3D

for one incident direction  $(\theta_{in}, \phi_{in})$ , display one hemisphere:



# visualising BRTF 2D

2D cuts along scattering plane through 3D dataset  
I prefer Cartesian plots over polar plots. example:



## medium sized intermission

... questions to math part ?

next to come: gonio-photometers

# light source types & parameters

beam parameter	Halogen	Xenon	laser diode	gas laser
power	+	++	-	-
radiance	-	+	++	+++
noise	++	+	+	+
polychromatic	+	+	-	-
incoherent	+	+	-	-

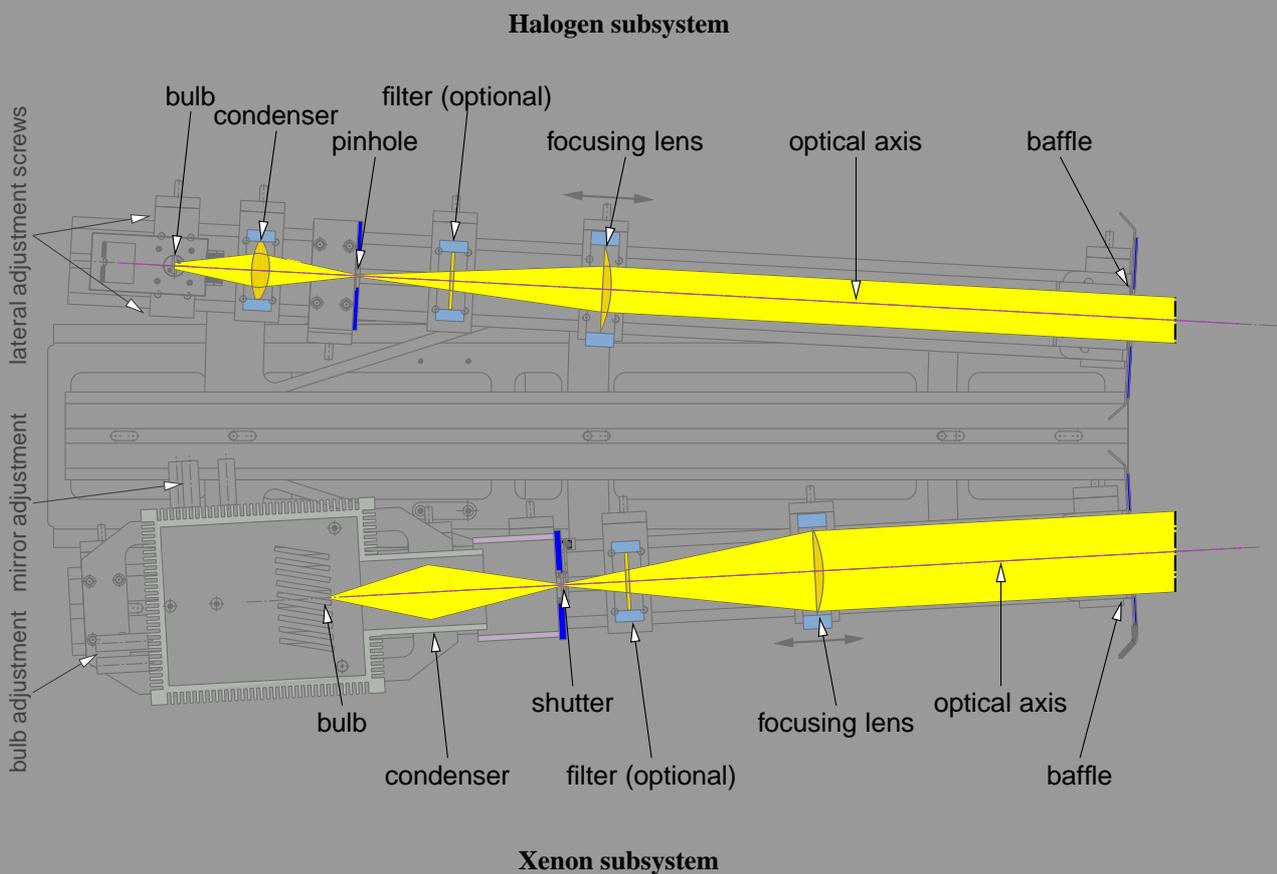
choice depends on:

- sample type
- wavelength range
- detector type

in the following: lamps kept at fixed positions

alternative concepts: moving lamp, fixed sample

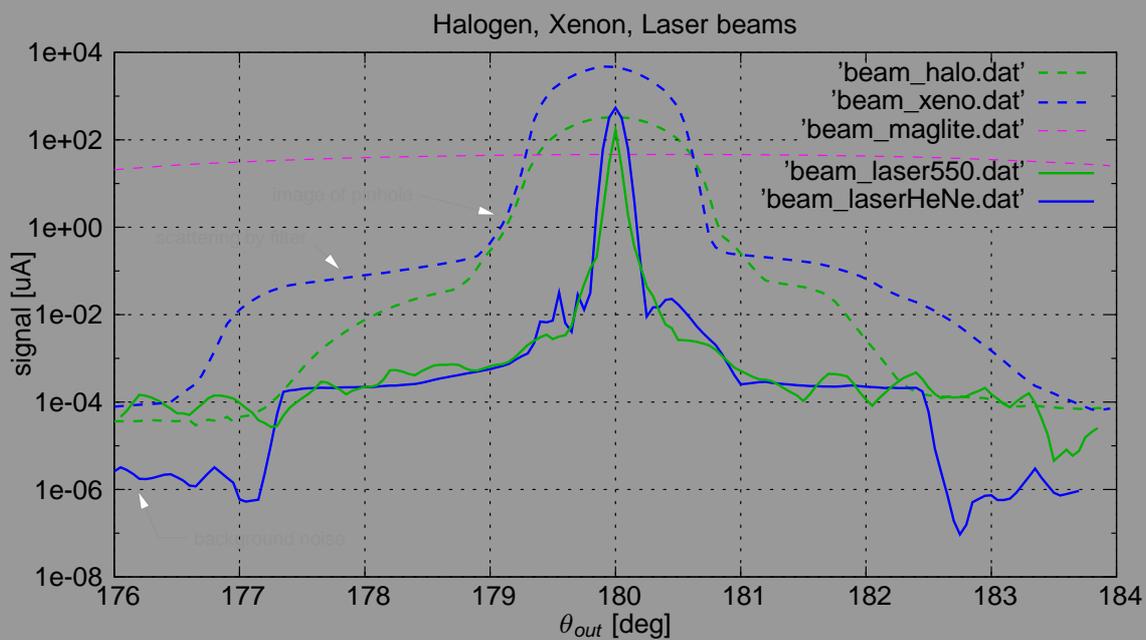
## example: pgll lamp subsystem



# example: pgII lamp subsystem



# example: beam profiles

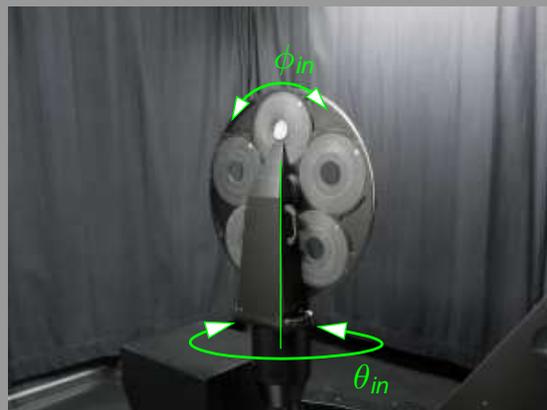
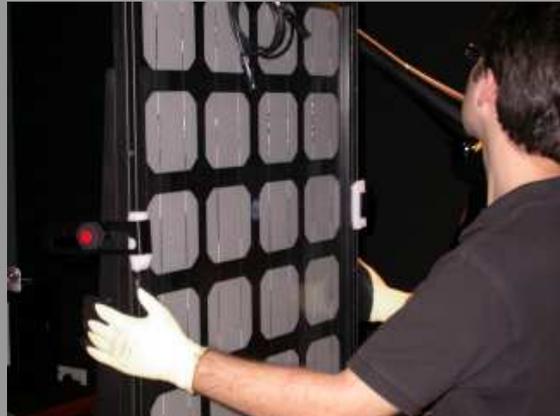


# sample mount

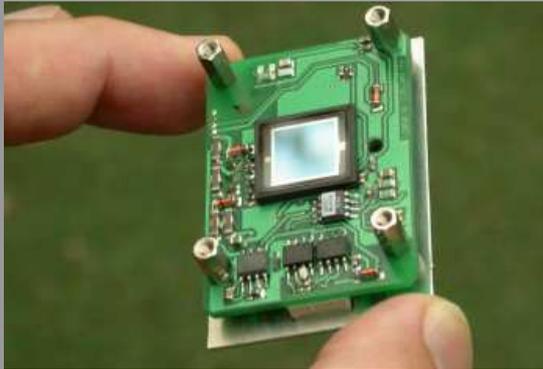
- fixes sample (securely)
- adjusts for  $\theta_{in}$ ,  $\phi_{in}$
- $\rightsquigarrow$  two degrees of freedom  
manual adjustment or automatic
- minimal self-shadowing
- shading of stray light

in the following: vertical sample mount assumed

# example sample mounts

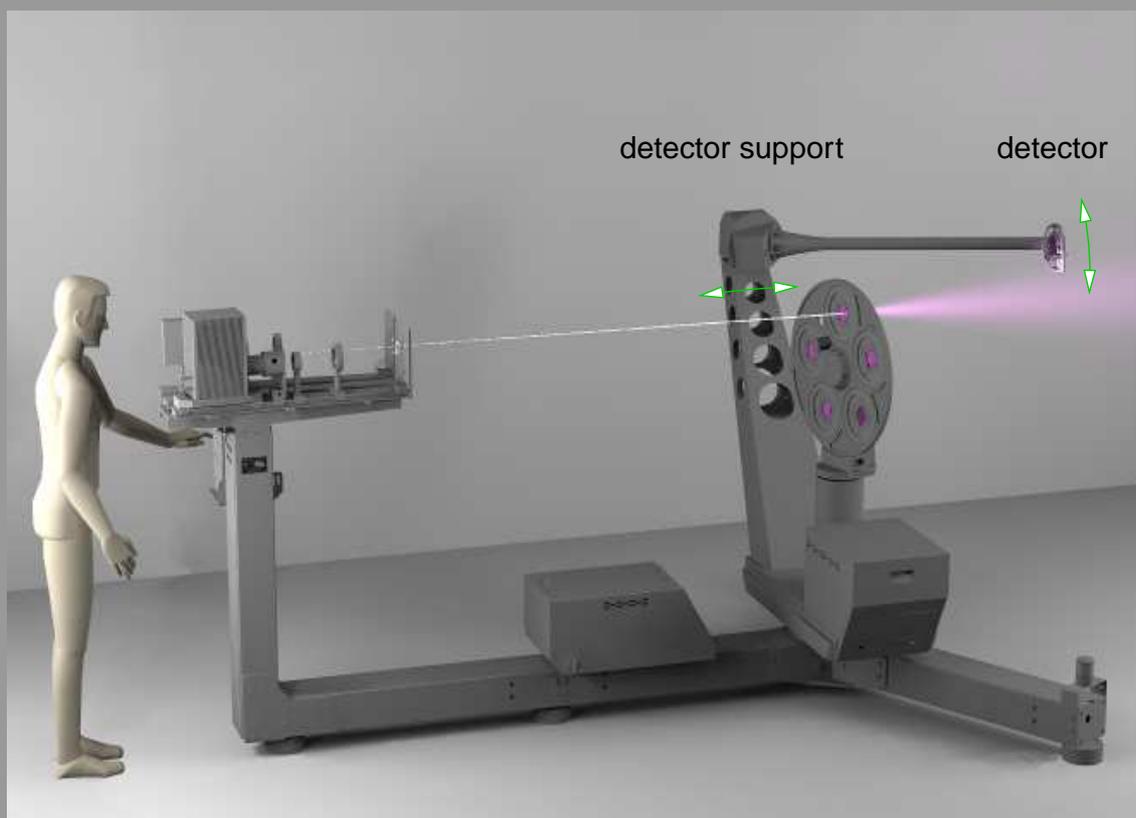


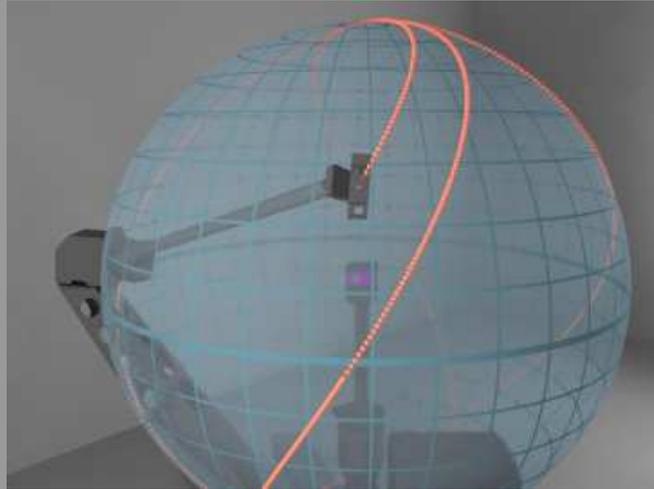
## detector parameters



- material and wavelength: Si (VIS), InGaAs (IR), etc
- principle: photo-diode, etc
- sample rate: measurements / second: 1Hz to 1kHz
- noise: *noise equivalent BRTF*, lowest measurable BRTF
- dynamic range:  $10^2$  at least,  $10^8$  better

## detector mechanics

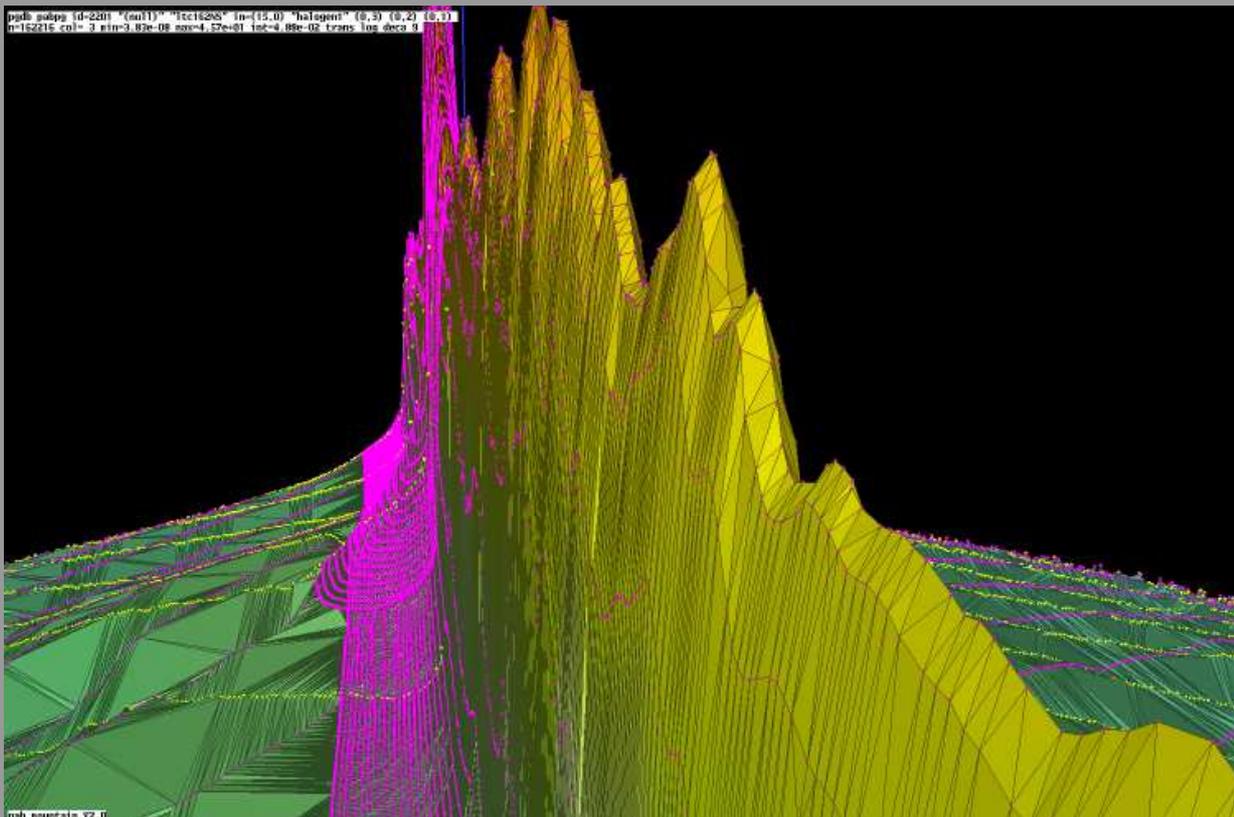




measurements-on-the-fly:

- avoid start-stop-cycles
- need excellent sync between position and data-acquisition
- need fast detector

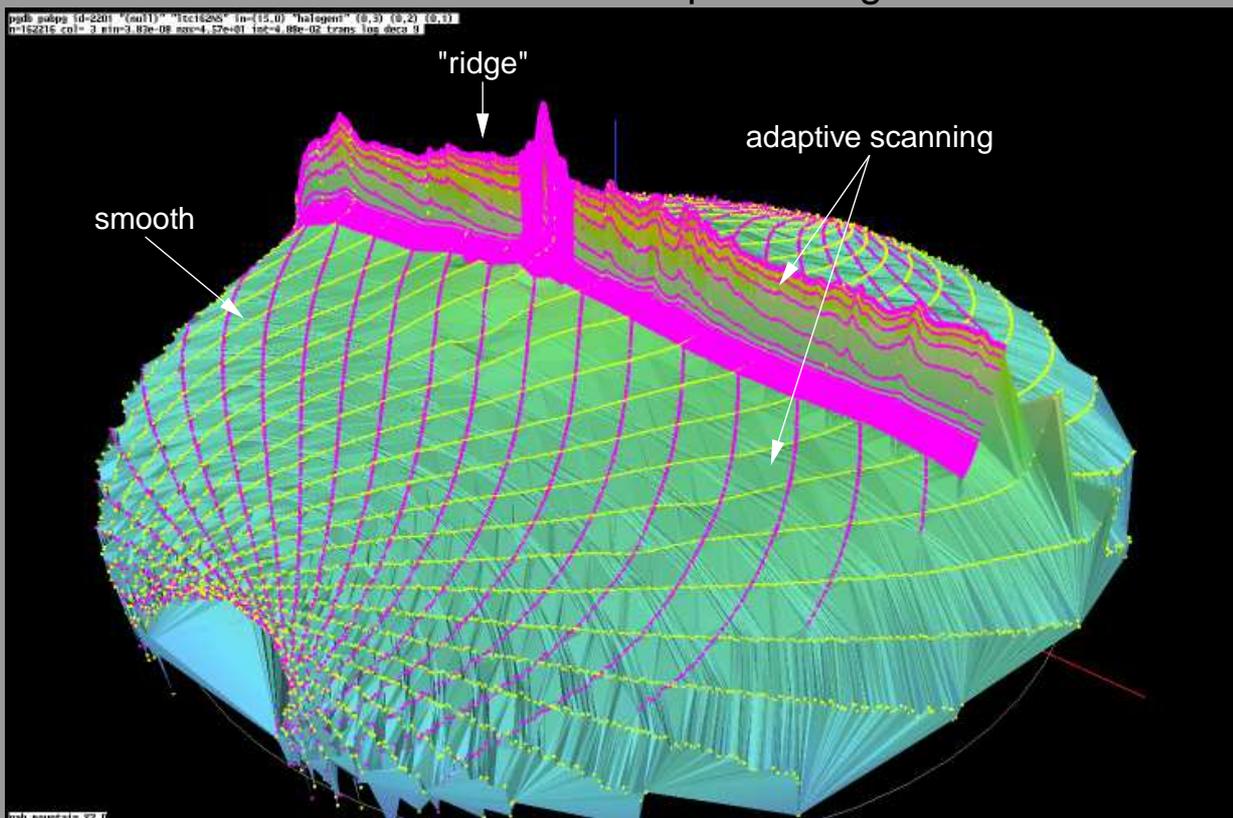
## discrete BRTF values versus continuous function



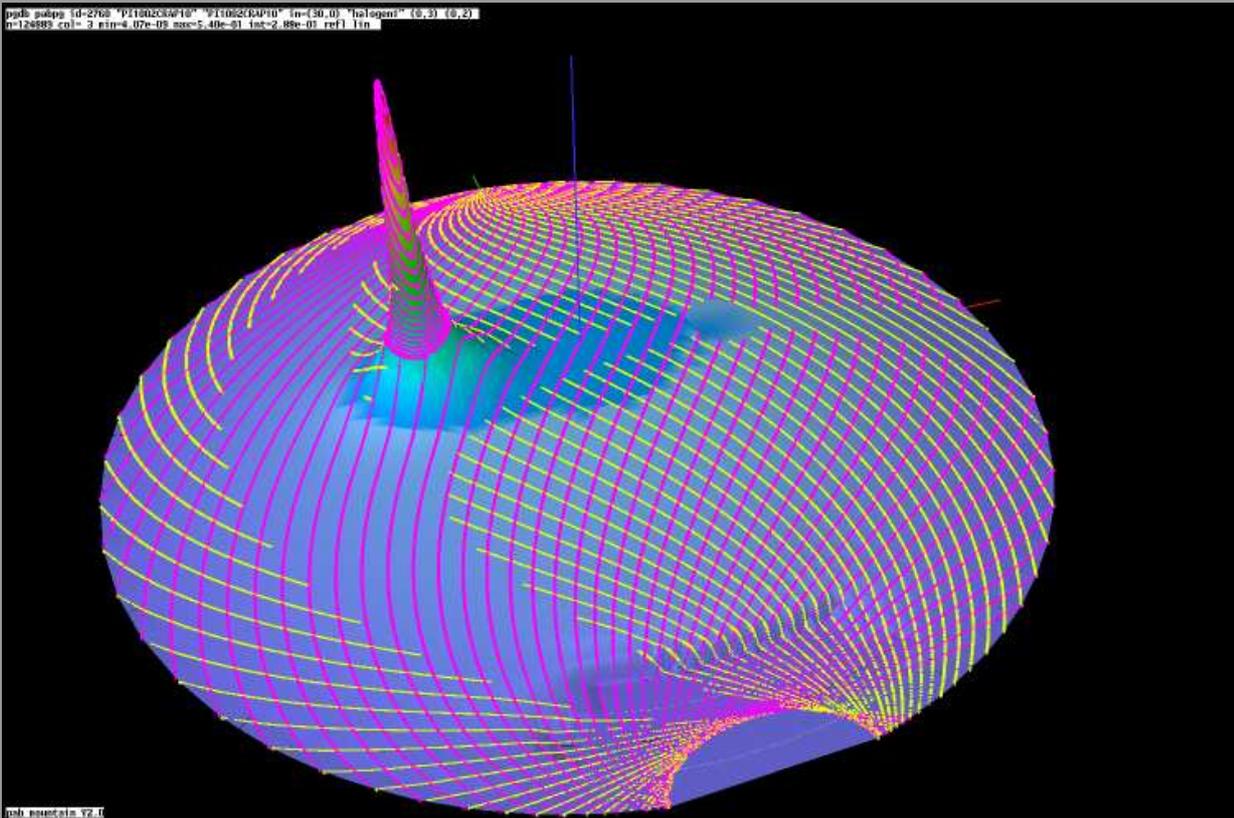
- in 3D,  $f(x_i, y_i)$  data points do *not* define a unique surface
- Delaunay triangulation recommended
- triangulation used for interpolation and integration
- $\rightsquigarrow$  good triangulation vital for BRTF data processing

## adaptive high angular resolution

BRTF consists of smooth areas and peaks/ridges:

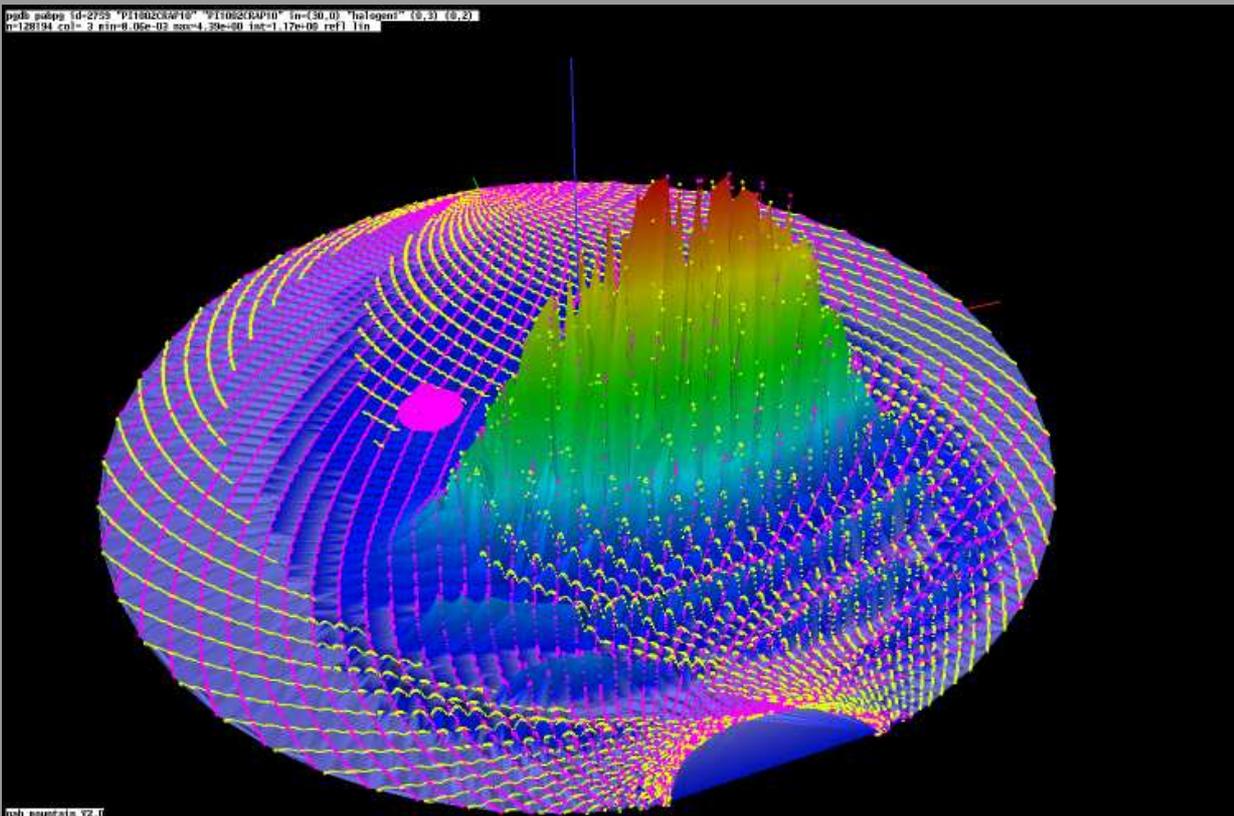


# checking for measurement errors implicitly



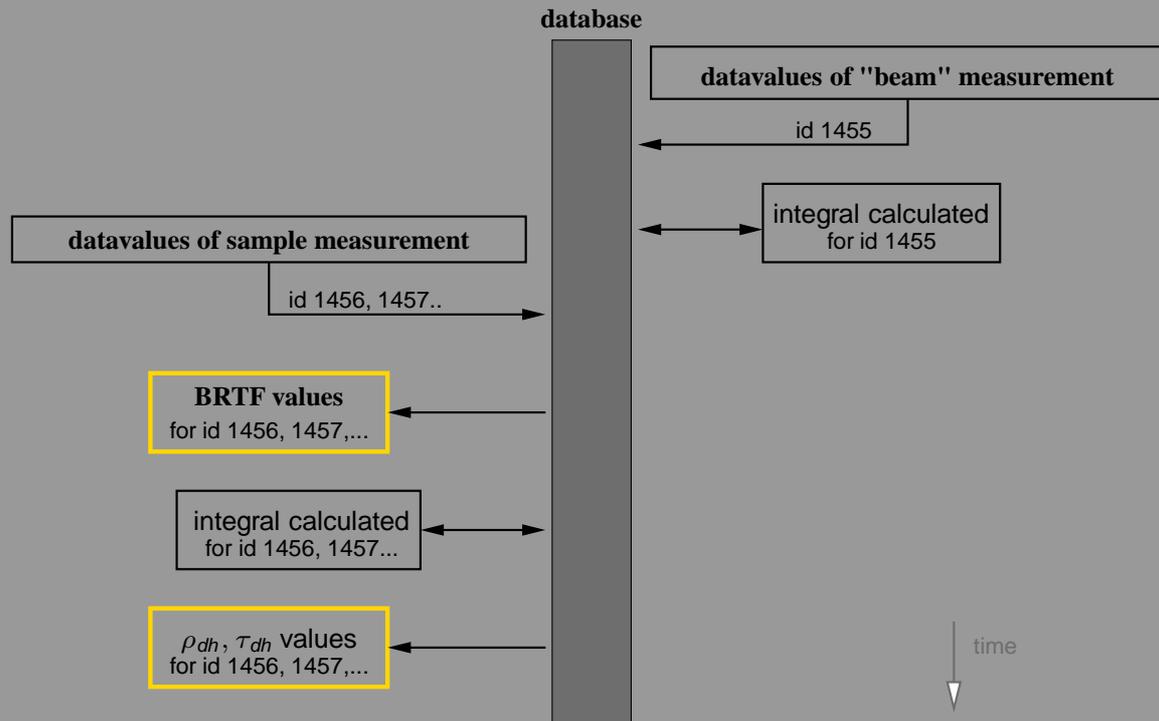
128109 data points all nicely smooth

# checking for measurement errors implicitly



ceiling lights on, 100Hz noise, (see SPIE 2010 paper for more)

## getting BRTF from raw data



## getting BRTF from raw data

advantages of using unscattered beam as reference

- illuminated area and detector distance cancel out
- no reference samples needed
- sensor identical for reference measurement

alternative way of doing measurements:

imaging gonio-photometers

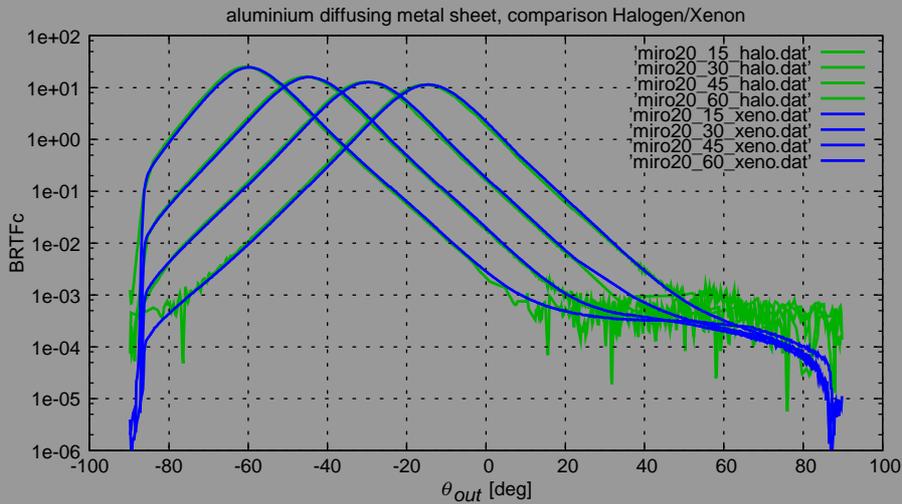
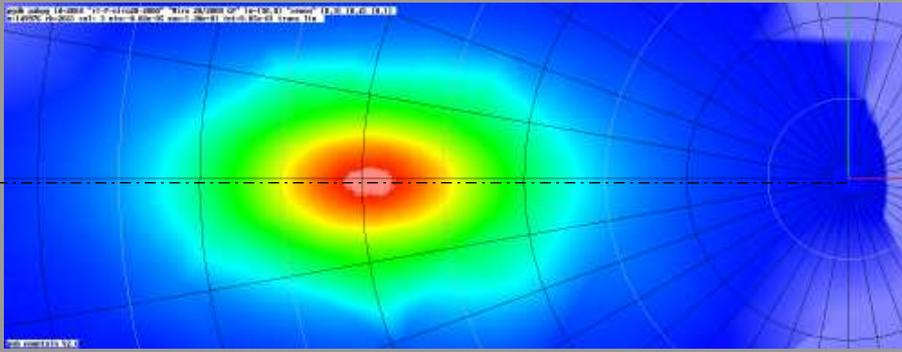
- + faster
- - more intermediate optics, not as general

## very short intermission

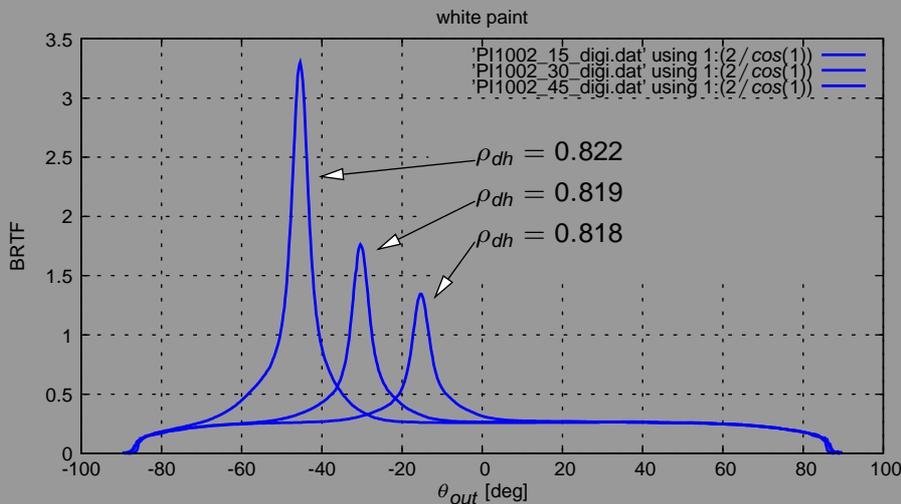
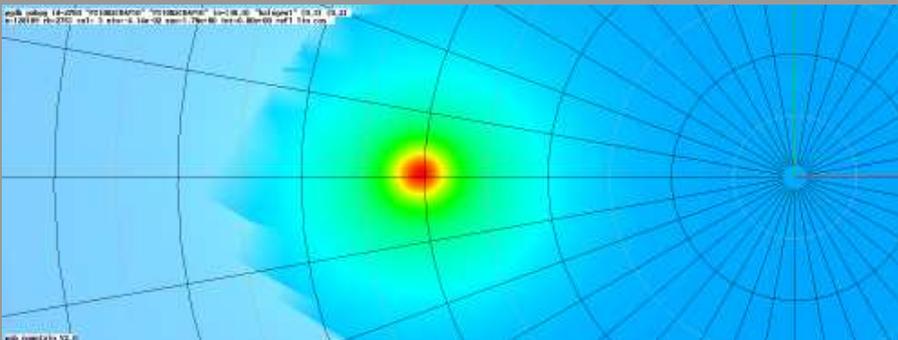
... questions to machine&measurement part ?

next to come: BRTF data &models

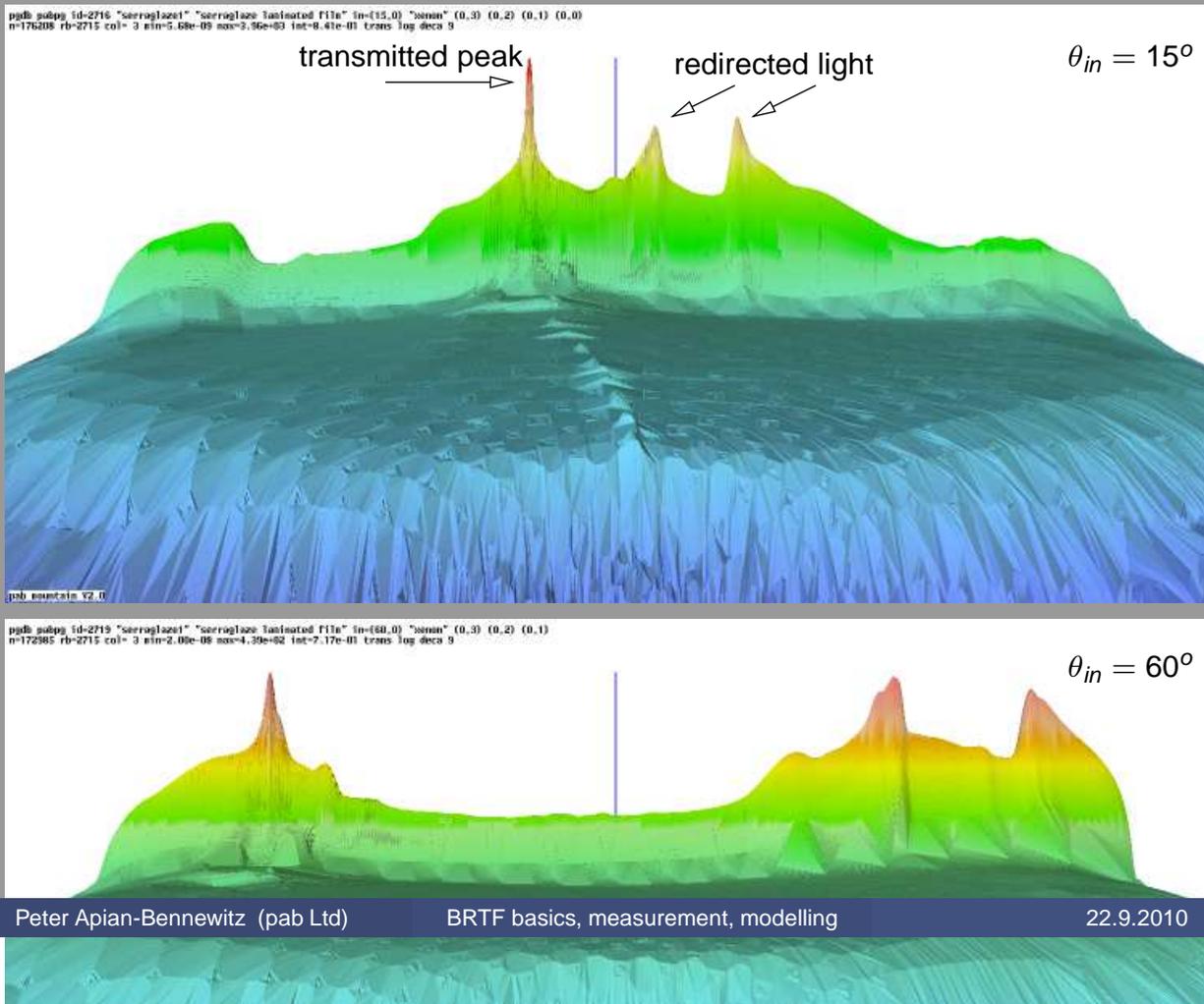
# example: aluminium



# example: white paint



# example: light redirecting, Serraglaze



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## angular resolution of incident and outgoing side

both sides are *not* symmetric:

- outgoing side:  
adaptive, high resolution ( $0.1^\circ$ )
- incident side:  
low resolution ( $10^\circ$ )

since:

Theorem

*in most cases the topology of a BRTF does not change between  $\vec{x}_{in}$  and  $\vec{x}_{in} + \Delta$ , for small  $\Delta$  (e.g.  $20^\circ$ )*

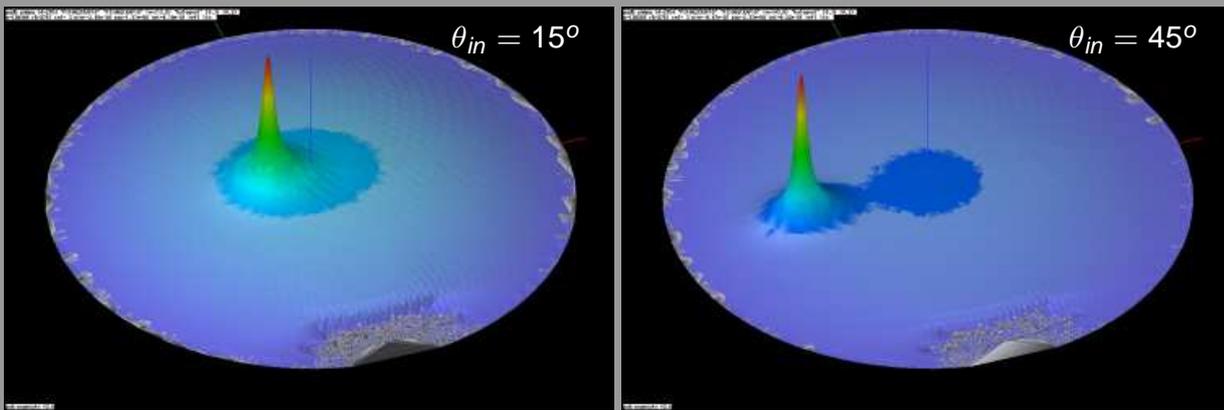
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# topology of a BRTF



- structure ("topology") of BRTF remains the same for  $\Delta$
- shape *parameters* change:  
peak position, peak height, peak width, background level
- $\rightsquigarrow$  intermediate  $\theta_{in}$  are predictable.
- $\rightsquigarrow$  measurements of finely resolved  $\theta_{in}$  are redundant
- $\rightsquigarrow$  don't waste time and data with these  
think of a good interpolation method

## getting BRTF into *Radiance*

problems to solve while importing data:

- interpolation between outgoing directions  $\vec{X}_{out}$ :  
triangulation, etc
- interpolation between incident directions  $\vec{X}_{in}$ :  
not a trivial problem
- optional data compression

ways into simulation program

- loading BRTF data-files directly
- fitting of parameters of internal model (`trans`, `plastic`)
- fitting of parameters of external model (`cal` files)
- loading of compressed/processed data

problems:

- adaptive scans produce non-grid data
- `brightdata`, `brtfddata` expect data on regular grids (depends on index function, but index into 100k points is cumbersome)
- no interpolation between incoming directions
- $\rightsquigarrow$  direct import is de-facto not supported

alternative way: interpolate data to regular grid

- coarse grid misses peaks
- fine grid increases memory requirements
- $\rightsquigarrow$  not a solution

## fitting parameter of function to BRTF data

process:

- fit  $f_{a_1 \dots a_N}(\theta_{out}, \phi_{out})$  to one dataset of incident direction  $\vec{x}_{in}$
- $\rightsquigarrow$  set of parameters  $a_1 \dots a_N$  or each  $(\theta_{in}, \phi_{in})$
- use functions  $g_i$  to fit  $a_i$  to  $(\theta_{in}, \phi_{in})$
- $\rightsquigarrow$  model complete for outgoing and incident directions
- best situation:  $a_i$  simple function of  $(\theta_{in}, \phi_{in})$

drawbacks:

- requires that  $f$  and choice of  $a_1 \dots a_N$  describe scattering well
- requires thinking for each material. not automatic.
- standard Levenberg-Marquardt method not 100% robust

note: see chapter 5 in author's 1995 dissertation (in German)

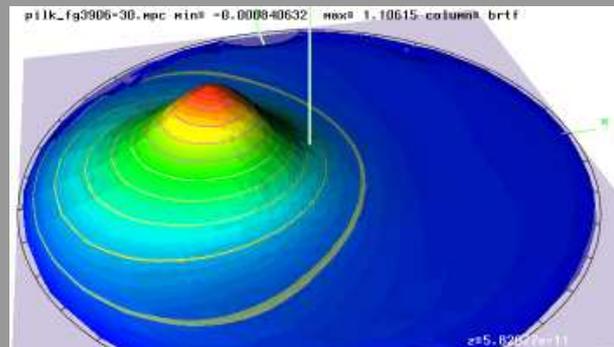
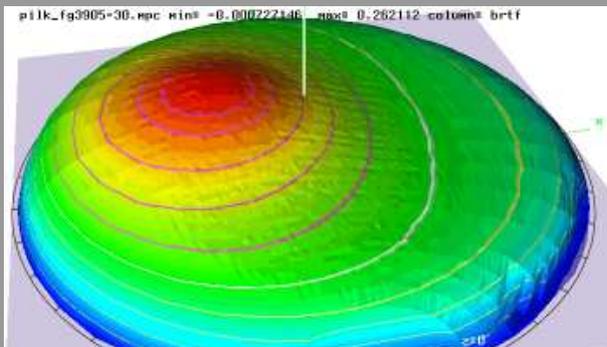
- internal to *Radiance* (e.g. trans)

$$BRTF_{trans} = \frac{a_6 (1 - a_7)}{\pi} + \frac{a_6 a_7}{\pi a_5^2 \sqrt{\cos(\theta_{in}) \cos(\theta_{out})}} \exp[(2 \cos(\theta_{half}) - 2)/a_5^2] \quad (6)$$

- external (example)

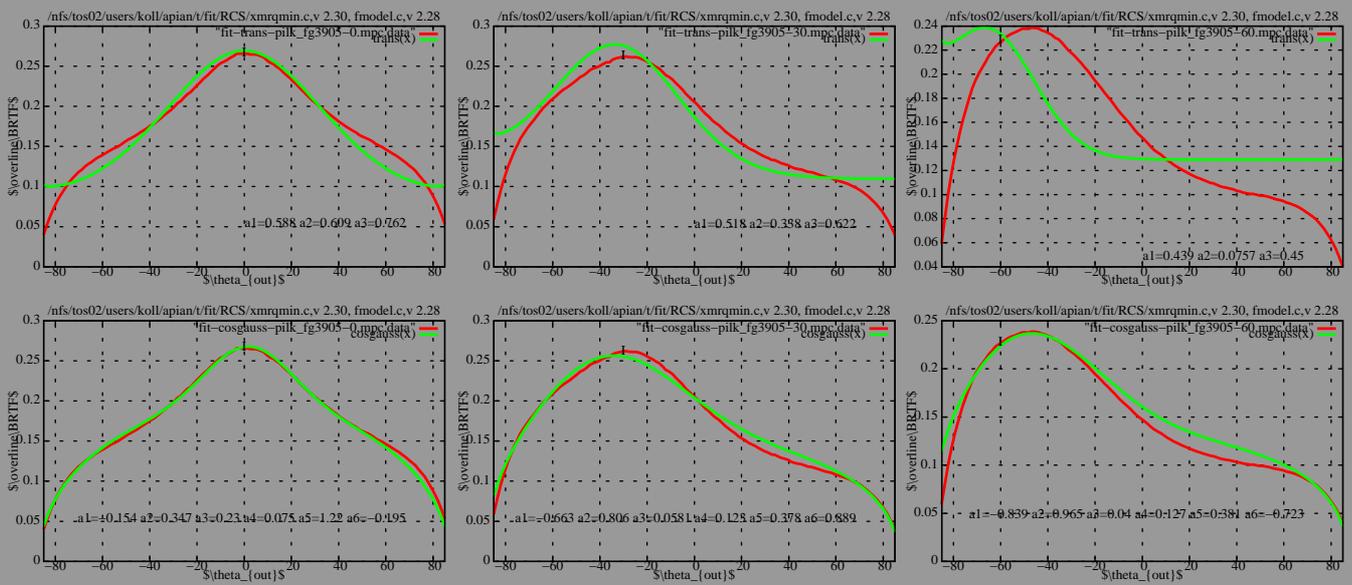
$$\begin{aligned} BRTF_{cosgauss} &:= a_1 + a_2 (\cos \theta)^{a_3} + a_4 \exp(-\beta^2 a_5) & (7) \\ \beta &:= \arccos[\cos(\theta) \cos(\alpha_{in} + a_6) - \sin(\theta) \cos(\phi_{out}) \sin(\alpha_{in} + 10a_6)] \\ \theta &:= \pi - \theta_{out} \end{aligned}$$

## example: fits to Pilkington fg3905, fg3906 in 1994



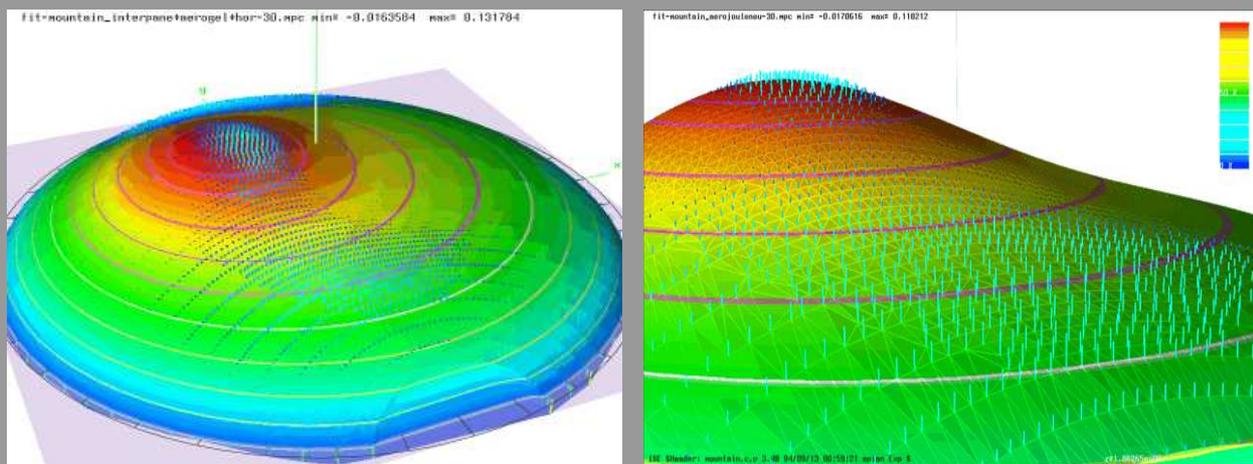
polymer/glass sandwich glazing,  
forward scattering, "milky" glazing

# fg3905 model comparison, in scattering-plane



red curves: measured data , green curves: BRTF model  
 top row: *trans* material,  $\theta_{in} = 0, 30, 60^\circ$   
 bottom row: suggested *cosgauss* model (cal file),  $\theta_{in} = 0, 30, 60^\circ$   
 note: see chapter 6 in author's 1995 dissertation for details

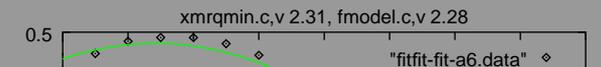
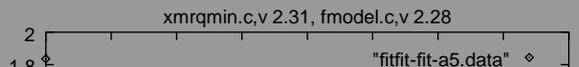
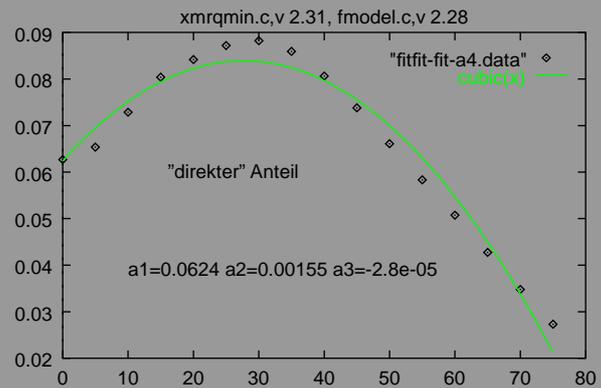
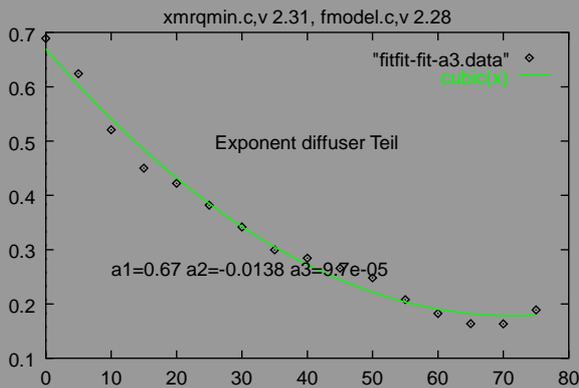
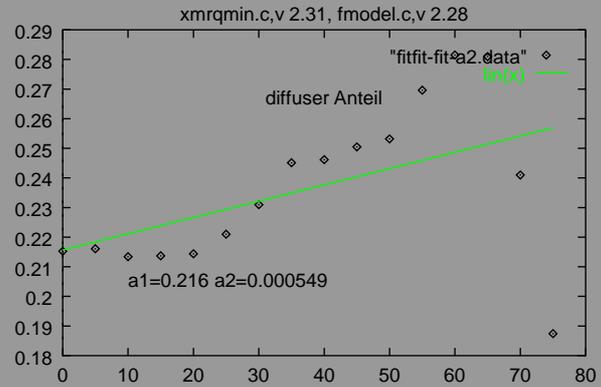
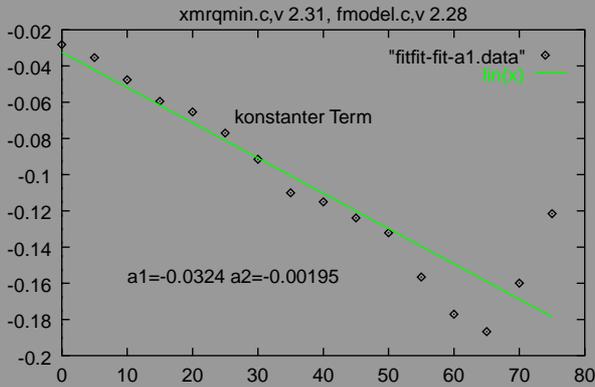
# fg3905 model comparison, off scattering-plane



deviation between model and data shown as spikes

fitting is done for *all* outgoing directions (not just in-plane)  
 model may deviate more outside the scattering plane

# example: Aerogel model, parameter variation



Breite des "direkten" Anteils

Veränderung des direkten Anteils

## conclusions for Radiance models

- current models don't match measured data well
- better built-in models or cal-files seem worth considering

## what *Radiance* is missing

- *ca/* file support for photon-map (and ambient calcs)  
~> support for general BRTF models
- BRTF import using non-fixed-grid data
- way to add internal models in a modular way  
(equivalent to a complete rewrite)

all these features require changes to the rendering core

~> non trivial work. But would be *very* useful in practice.

## ...thanks

last slide.

- physics is fun
- happy rendering
- thank you for joining workshop and thanks for your attention

latest papers on pglI gonio-photometer & links:

- "Experimental validation of bidirectional reflection and transmission distribution measurements of specular and scattering materials," SPIE 2010, Brüssel, <http://dx.doi.org/10.1117/12.854011>
- "New scanning gonio-photometer for extended BRTF measurements" SPIE 2010, San Diego, <http://dx.doi.org/10.1117/12.860889>
- currently installed pglI gonio-photometers: SERIS Singapore, LBNL Berkeley, pab Freiburg, industrial client Europe
- pglI gonio-photometer webpage: <http://www.pab.eu>
- author's 1995 Phd: <http://www.pab-opto.de/pers/phd/>

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